

Mathematica Pannonica
2/1 (1991), 49 – 61

AN INITIAL AND BOUNDARY VALUE PROBLEM FOR NONLI- NEAR COMPOSITE TYPE SYS- TEMS OF THREE EQUATIONS*

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Received December 1989

AMS Subject Classification: 35 M 05, 30 G 20, 30 E 25

Keywords: composite type systems, elliptic systems, a priori estimate, Schauder imbedding

Abstract: Boundary value problems for systems of composite type were investigated by A. Dzhravaev, see [1]. Using the theory of singular integral equations in [1] linear problems for linear systems of three and of four equa-

* This work was done while the second and third authors visited the Free University Berlin in fall 1988 on exchange programs between the Educational State Commission of P. R. China and DFG and DAAD, respectively.

tions having one and two real characteristics, respectively are treated. Here a nonlinear problem for a nonlinear system of three equations is studied by utilizing a method from the theory of elliptic systems (see e.g. [3],[4]) based on Schauder imbedding. The case of three equations is important in particular because every elliptic second order equation in two independent variables may be reduced to a first order composite type system of three equations.

1. Formulation of the initial and boundary value problem

In this paper, we consider the nonlinear system of first order composite type equations

$$(1.1) \quad \begin{cases} \omega_{\bar{z}} = F(z, \omega, \omega_z, s), \\ F = Q_1 \omega_z + Q_2 \bar{\omega}_{\bar{z}} + A_1 \omega + A_2 \bar{\omega} + A_3 s + A_4, \end{cases}$$

$$(1.2) \quad \begin{cases} s_y = G(z, \omega, s), \\ G = B_1 \omega + B_2 \bar{\omega} + B_3 s + B_4, \end{cases}$$

in a bounded simply connected domain D , where

$$\begin{aligned} Q_j &= Q_j(z, \omega, \omega_z, s), & j &= 1, 2, & A_j &= A_j(z, \omega, s), \\ B_j &= B_j(z, \omega, s), & j &= 1, \dots, 4, \end{aligned}$$

and $\omega(z)$, Q_j , A_j , B_j ($j = 1, 2$), A_4 are complex valued functions, $B_2 = \bar{B}_1$, $s(z)$, A_3 , B_j ($j = 3, 4$) are real valued functions. For the sake of convenience, we may assume that D is the unit disk and the lower boundary of D is $\gamma = \{|z| = 1, y \leq 0\}$. We suppose that system (1.1) and (1.2) satisfy the following condition.

Condition C

- (1) $Q_j(z, \omega, U, s)$, $j = 1, 2$, $A_j(z, \omega, s)$, $j = 1, \dots, 4$ are measurable in $z \in D$ for all continuous functions $\omega(z)$, $s(z)$ and all measurable functions $U(z)$ on \bar{D} , satisfying

$$(1.3) \quad \begin{aligned} L_p[A_j(z, \omega(z), s(z)), \bar{D}] &\leq k_0 < \infty, & j &= 1, 2, 4, \\ L_p[A_3(z, \omega(z), s(z)), \bar{D}] &\leq \varepsilon, \end{aligned}$$

where $p(> 2)$, $k_0(> 0)$ and $\varepsilon(> 0)$ are positive constants.

- (2) The above mentioned functions are continuous in $\omega \in \mathcal{C}$ (the complex plane) and $s \in \mathbb{R}$ (the real axis) for almost every point $z \in D$ and $U \in \mathcal{C}$.
- (3) The complex equation (1.1) satisfies the uniform ellipticity condition

$$(1.4) \quad |F(z, \omega, U_1, s) - F(z, \omega, U_2, s)| \leq q_0 |U_1 - U_2|,$$

for almost every point $z \in D$ and $\omega, U_1, U_2 \in \mathcal{C}$, $s \in \mathbb{R}$, in which $q_0(< 1)$ is a non-negative constant.

- (4) $B_j(z, \omega, s)$ ($j = 1, \dots, 4$), $G(z, \omega, s)$ are continuous for $z \in \bar{D}$ for all Hölder continuous functions $\omega_j(z), s_j(z) \in C_\beta(\bar{D})$ ($j = 1, 2$) satisfying

$$(1.5) \quad \begin{cases} C_\beta[B_j(z, \omega_1, s_1), \bar{D}] & \leq k_0 < \infty, \quad j = 1, \dots, 4, \\ G(z, \omega_1, s_1) - G(z, \omega_2, s_2) & = B_1^*(\omega_1 - \omega_2) + B_2^*(\omega_1 - \omega_2) + \\ & + B_3^*(s_1 - s_2), \end{cases}$$

in which $C_\beta[B_j^*, \bar{D}] \leq k_0, \beta$ ($0 < \beta < 1$) is real, for $j = 1, 2, 3$.

For system (1.1) and (1.2) we discuss the following nonlinear initial and boundary value problem.

Problem A

$$(1.6) \quad \operatorname{Re}[\overline{\lambda(t)}\omega(t)] = P(t, \omega, s), t \in \Gamma = \partial D,$$

$$(1.7) \quad a(t)s(t) = Q(t, \omega, s), t \in \gamma.$$

Here $\lambda(t), P(t, \omega, s)$ are Hölder continuous functions, $|\lambda(t)| = 1$, and $\lambda(t), P_0(t) = P(t, 0, 0), P(t, \omega, s)$ satisfy

$$(1.8) \quad \begin{cases} C_\alpha[\lambda[t(\zeta)], L] \leq k_0, C_\alpha[P_0[t(\zeta)], L] \leq k_1, L = \zeta(\Gamma), \\ C_\alpha[P(t(\zeta), \omega_1, s_1) - P(t(\zeta), \omega_2, s_2), L] \leq \\ \leq \varepsilon\{C_\alpha[\omega_1 - \omega_2, L] + C_\alpha[s_1 - s_2, \ell]\}, \ell = \zeta(\gamma), \end{cases}$$

for all $\omega_j[t(\zeta)] \in C_\alpha(L), s_j(t) \in C_\alpha(\ell)$, $j = 1, 2$, where $\zeta(z)$ is the homeomorphic solution to the Beltrami equation $\zeta_{\bar{z}} = q(z)\zeta_z$ with a proper q ($|q(z)| \leq q_0 < 1$) which maps D onto the unit disk H such that $\zeta(0) = 0, \zeta(1) = 1; z(\zeta)$ is the inverse function of $\zeta(z)$, k_1 and ε are positive constants. Moreover, $|a(t)| = 1, Q_0(t) = Q(t, 0, 0)$ and $Q(t, \omega, s)$ satisfy

$$(1.9) \quad \begin{cases} C_\beta[Q_0(t), \gamma] \leq k_2, \\ C_\beta[Q(t, \omega_1, s_1) - Q(t, \omega_2, s_2), \gamma] \leq \\ \leq k_2 C_\beta(\omega_1 - \omega_2, \gamma) + \varepsilon C_\beta(s_1 - s_2, \gamma), \end{cases}$$

in which k_2 is a positive constant. Obviously **Problem A** is not necessarily solvable. Hence we consider the modified initial-boundary value problem (**Problem B**) where (1.6) is replaced by

$$(1.10) \quad \operatorname{Re} [\overline{\lambda(t)} \omega(t)] = P(t, \omega, s) + h(t), \quad t \in \Gamma,$$

with

$$(1.11) \quad h(t) = \begin{cases} 0, & t \in \Gamma, \text{ if } K \geq 0, \quad K = \frac{1}{2\pi} \Delta_\Gamma \arg \lambda(t), \\ h_0 + \operatorname{Re} \sum_{m=1}^{-K-1} (h_m^+ + ih_m^-) t^m, & t \in \Gamma, \text{ if } K < 0, \end{cases}$$

where h_0, h_m^\pm ($m = 1, \dots, -K - 1$) are unknown real constants to be determined appropriately. If $K \geq 0$, we assume that the solution $\omega(z)$ to **Problem A** satisfies the side conditions

$$(1.12) \quad \operatorname{Im} [\overline{\lambda(a_j)} \omega(a_j)] = b_j, \quad j = 1, \dots, 2K + 1,$$

where a_j ($j = 1, \dots, 2K + 1$) are distinct points on Γ , and b_j ($j = 1, \dots, 2K + 1$) are real constants with the condition $|b_j| \leq k_1$.

In the following, we first give an a priori estimate of solutions to **Problem B**. Afterwards, we prove **Problem B** and **Problem A** to be solvable by using the *Schauder fixed-point theorem*. Under some more restrictions, we can discuss the uniqueness of the solution to **Problem B**.

2. A priori estimate of solutions to the initial and boundary value problem

First of all, we discuss the system of first order composite type equations

$$(2.1) \quad \begin{cases} \omega_{\bar{z}} = F^*(z, \omega, \omega_z, s), \\ F^* = Q_1 \omega_z + Q_2 \bar{\omega}_{\bar{z}} + A_1 \omega + A_2 \bar{\omega} + A, \end{cases}$$

$$(2.2) \quad \begin{cases} s_y = G^*(z, \omega, s), \\ G^* = B_3 s + B, \end{cases}$$

together with the following linear initial and boundary value problem.

Problem B*

$$(2.3) \quad \operatorname{Re}[\overline{\lambda(t)}\omega(t)] = P_0(t) + h(t), \quad t \in \Gamma,$$

$$(2.4) \quad \operatorname{Im}[\overline{\lambda(a_j)}\omega(a_j)] = b_j, \quad j = 1, \dots, 2K + 1, \quad K \geq 0,$$

$$(2.5) \quad a(t)s(t) = Q_0(t), \quad t \in \gamma,$$

where Q_j, A_j ($j = 1, 2$), $B_3, \lambda, P_0, h, b_j, a, Q_0$ are defined as in 1, and $A = A(z, \omega, s)$, $B = B(z, \omega, s)$ are similar to A_4, B_4 , but satisfying the conditions

$$(2.6) \quad L_p[A, \overline{D}] \leq k_3, \quad C_\beta[B, \overline{D}] \leq k_4,$$

for any $\omega(z), s(z) \in C_\beta(\overline{D})$, in which k_3, k_4 are non-negative constants.

Lemma 2.1. *If $[\omega(z), s(z)]$ is a solution to Problem B* for the system (1.1), (2.2), then $[\omega(z), s(z)]$ satisfies the estimates*

$$(2.7) \quad C_\beta[\omega, \overline{D}] \leq M_1(k_1 + k_3), \quad L_{p_0}[|\omega_z| + |\omega_{\bar{z}}|, \overline{D}] \leq M_2(k_1 + k_3),$$

$$(2.8) \quad C_\beta^*[s, \overline{D}] := C_\beta[s, \overline{D}] + C[s_y, \overline{D}] \leq M_3(k_2 + k_4),$$

where $M_j = M_j(q_0, p_0, k_0, \alpha, k, K)$, $j = 1, 2, 3$, $k = (k_1, k_2, k_3, k_4)$, $\beta = \min(\alpha, 1 - \frac{2}{p_0})$, $p_0 = \min(p, \frac{1}{1-\alpha})$.

Proof. Substituting the solution $[\omega, s]$ to Problem B* into the complex system (2.1), (2.2), and assuming that $k' = \max(k_1, k_3) > 0$, $k'' = \max(k_2, k_4) > 0$, we put

$$(2.9) \quad W(z) = \frac{\omega(z)}{k'}, \quad S(z) = \frac{s(z)}{k''}.$$

It is clear that $W(z)$ is a solution to the boundary value problem

$$(2.10) \quad W_{\bar{z}} = Q_1 W_z + Q_2 \overline{W_{\bar{z}}} + A_1 W + A_2 \overline{W} + \frac{A}{k'},$$

$$(2.11) \quad \operatorname{Re}[\overline{\lambda(t)} W(t)] = \frac{P_0(t) + h(t)}{k'}, \quad t \in \Gamma,$$

$$(2.12) \quad \operatorname{Im}[\overline{\lambda(a_j)} W(a_j)] = \frac{b_j}{k'}, \quad j = 1, \dots, 2K + 1, \quad K \geq 0.$$

Noting that

$$(2.13) \quad L_p \left[\frac{A}{k'}, \overline{D} \right] \leq 1, \quad C_\alpha \left[\frac{P_0(t(\zeta))}{k'}, L \right] \leq 1, \quad \left| \frac{b_j}{k'} \right| \leq 1,$$

and according to Theorem 5.6 of Chapter 5 in [3] or Theorem 4.3 of Chapter 2 in [4], we know that $W(z)$ satisfies the estimate

$$(2.14) \quad C_\beta[W, \overline{D}] \leq M_1, \quad L_{p_0}[|W_{\bar{z}}| + |W_z|, \overline{D}] \leq M_2.$$

Moreover, $S(z)$ is a solution to the initial value problem

$$(2.15) \quad S_y = B_3 S + \frac{B}{k''},$$

$$(2.16) \quad a(t)S(t) = \frac{Q_0(t)}{k''}, \quad t \in \gamma,$$

where $C_\beta \left[\frac{B}{k''}, \overline{D} \right] \leq 1$, $C_\beta \left[\frac{Q_0}{k''}, \gamma \right] \leq 1$. On the basis of Theorem 2.4 in [2], $S(z)$ can be seen to satisfy the estimate

$$(2.17) \quad C_\beta^*[S, \overline{D}] \leq M_3.$$

From (2.14), (2.17) it follows that (2.7), (2.8) for $k' > 0$, $k'' > 0$ are true. If $k' = 0$ or $k'' = 0$, then (2.7), (2.8) for $k' = \varepsilon > 0$ or $k'' = \varepsilon > 0$ hold. Letting ε tend to 0, we obtain (2.7), (2.8) for $k' = 0$ or $k'' = 0$. \diamond

Theorem 2.2. *Let the complex system (1.1) and (1.2) satisfy Condition C and the constant ε in (1.3), (1.8) and (1.9) be small enough. Then the solution $[\omega(z), s(z)]$ to Problem B for (1.1), (1.2) satisfies the estimate*

$$(2.18) \quad U = C_\beta[\omega, \overline{D}] + L_{p_0}[|\omega_z| + |\omega_z|, \overline{D}] \leq M_4,$$

$$(2.19) \quad V = C_\beta^*[s, \overline{D}] \leq M_5,$$

where $M_j = M_j(q_0, p_0, k_0, a, k, K)$, $j = 4, 5$.

Proof. Let the solution $[\omega(z), s(z)]$ be inserted into the complex system (1.1), (1.2), the boundary condition (1.10), the side condition (1.12) and the initial condition (1.7). We see that $A = A_3 s + A_4$, $B = B_1 \omega + B_2 \bar{\omega} + B_4$, $P(t, \omega, s)$, $Q(t, \omega, s)$, b_j satisfy

$$(2.20) \quad L_p[A, \overline{D}] \leq \varepsilon C[s, \overline{D}] + L_p[A_4, \overline{D}] \leq \varepsilon C[s, \overline{D}] + k_0,$$

$$(2.21) \quad C_\beta[B, \overline{D}] \leq C_\beta[B_1 \omega + B_2 \bar{\omega}, \overline{D}] + C_\beta[B_4, \overline{D}] \leq 2k_0 C_\beta[\omega, \overline{D}] + k_0,$$

$$(2.22) \quad \begin{aligned} C_\alpha[P, L] &\leq C_\alpha[P_0(t(\zeta)), L] + C_\alpha[P[t(\zeta), \omega, s] - P_0[t(\zeta)], L] \leq \\ &\leq k_1 + \varepsilon \{C_\alpha[\omega, L] + C_\beta[s, \ell]\}, \end{aligned}$$

$$(2.23) \quad |b_j| \leq k_1, \quad j = 1, \dots, 2K + 1, \quad K \geq 0,$$

$$(2.24) \quad \begin{aligned} C_\beta[Q, \gamma] &\leq C_\beta[Q_0(t), \gamma] + k_0 C_\beta[\omega, \gamma] + \varepsilon C_\beta[s, \gamma] \leq \\ &\leq k_2 + k_2 C_\beta[\omega, \overline{D}] + \varepsilon C_\beta[s, \overline{D}]. \end{aligned}$$

Using (2.7) and (2.8) we have

$$\begin{aligned}
 U &\leq (M_1 + M_2)\{\varepsilon C[s, \bar{D}] + k_0 + k_1 + \varepsilon[C_\alpha(\omega, L) + C_\alpha[s, \ell]]\} \leq \\
 (2.25) \quad &\leq (M_1 + M_2)[k_0 + k_1 + \varepsilon C_\beta(\omega, \bar{D}) + \varepsilon C_\beta(s, \bar{D})] \leq \\
 &\leq (M_1 + M_2)(k_0 + k_1 + \varepsilon U + \varepsilon V),
 \end{aligned}$$

$$\begin{aligned}
 (2.26) \quad V &\leq M_3[2k_0 C_\beta(\omega, \bar{D}) + k_0 + k_2 + k_2 C_\beta(\omega, \bar{D}) + \varepsilon C_\beta(s, \bar{D})] \leq \\
 &\leq M_3[k_0 + k_2 + (2k_0 + k_2)U + \varepsilon V].
 \end{aligned}$$

Choosing the constant ε so small that

$$(M_1 + M_2)\varepsilon \leq \frac{1}{2}, \quad M_3[1 + 2(2k_0 + k_2)(M_1 + M_2)]\varepsilon \leq \frac{1}{2},$$

one can show

$$(2.27) \quad U \leq \frac{(M_1 + M_2)(k_0 + k_1 + \varepsilon V)}{1 - (M_1 + M_2)\varepsilon} \leq 2(M_1 + M_2)(k_0 + k_1 + \varepsilon V),$$

$$\begin{aligned}
 (2.28) \quad V &\leq M_3[k_0 + k_2 + 2(2k_0 + k_2)(M_1 + M_2)(k_0 + k_1 + \varepsilon V) + \varepsilon V] \leq \\
 &\leq \frac{M_3[k_0 + k_2 + 2(2k_0 + k_2)(k_0 + k_1)(M_1 + M_2)]}{1 - M_3[1 + 2(2k_0 + k_2)(M_1 + M_2)]\varepsilon} \leq \\
 &\leq 2M_3[k_0 + k_2 + 2(2k_0 + k_2)(k_0 + k_1)(M_1 + M_2)] = M_5,
 \end{aligned}$$

$$(2.29) \quad U \leq 2(M_1 + M_2)(k_0 + k_1 + \varepsilon M_5) = M_4. \quad \diamond$$

3. Solvability of the initial and boundary value problem

First we prove the existence of solutions to Problem B for the system

$$(3.1) \quad \begin{cases} \omega_{\bar{z}} = F(z, \omega, \omega_z), & F = Q_1 \omega_z + Q_z \bar{\omega}_{\bar{z}} + A_1 \omega + A_z \bar{\omega} + A_3, \\ Q_j = Q_j(z, \omega_z), & j = 1, 2, A_j = A_j(z), \quad j = 1, 2, 3, \end{cases}$$

and (1.2) by using the parameter extension method, and then verify the existence of solutions to Problem B for the system (1.1) and (1.2) by using Theorem 2.2 and the *Schauder fixed point theorem*. Finally, we give conditions for Problem A for (1.1), (1.2) to be solvable.

Theorem 3.1. *Let the system (3.1), (1.2) satisfy Condition C and the constant ε be small enough. Then Problem B for (3.1), (1.2) is solvable.*

Proof. We consider the following initial boundary value problem with parameter t ($0 \leq t \leq 1$).

Problem B'

$$(3.2) \quad \omega_{\bar{z}} = tF(z, \omega, \omega_z) + A(z) \text{ in } D, \quad A \in L_{p_0}(\bar{D}),$$

$$(3.3) \quad \operatorname{Re} [\overline{\lambda(z)} \omega(z)] = tP(z, \omega, s) + p(z) + h(z), \text{ on } \Gamma, \quad p \in C_\beta(\Gamma),$$

$$(3.4) \quad \operatorname{Im} [\overline{\lambda(a_j)} \omega(a_j)] = b_j, \quad j = 1, \dots, 2K + 1, \quad K \geq 0,$$

$$(3.5) \quad s_y = tG(z, \omega, s) + B(z) \text{ in } D, \quad B \in C_\beta(\bar{D}),$$

$$(3.6) \quad a(z)s(z) = tQ(z, \omega, s) + q(z) \text{ on } \gamma, \quad q \in C_\beta(\gamma).$$

When $t = 0$, Problem B' has a unique solution $[\omega(z), s(z)]$ with $\omega \in C_\beta(\bar{D})$, $s \in C_\beta^*(\bar{D})$ - see [2], [3] and [4].

Assuming that Problem B' for t_0 ($0 \leq t_0 \leq 1$) is solvable, we will prove that there exists a positive constant δ such that Problem B' on

$$(3.7) \quad E = \{t | t - t_0| \leq \delta, 0 \leq t \leq 1\}$$

for any $A \in L_{p_0}(\bar{D})$, $B \in C_\beta(\bar{D})$, $p \in C_\beta(\Gamma)$ and $q \in C_\beta(\gamma)$ has a unique solution $[\omega(z), s(z)]$, $\omega \in C_\beta(\bar{D}) \cap W_{p_0}^1(D)$, $s \in C_\beta^*(\bar{D})$.

We rewrite (3.2) - (3.6) as

$$(3.8) \quad \omega_{\bar{z}} - t_0 F(z, \omega, \omega_z) = (t - t_0) F(z, \omega, \omega_z) + A(z),$$

$$(3.9) \quad \operatorname{Re} [\overline{\lambda(z)} \omega(z)] - t_0 P(z, \omega, s) = (t - t_0) P(z, \omega, s) + p(z) + h(z),$$

$$(3.10) \quad \operatorname{Im} [\overline{\lambda(a_j)} \omega(a_j)] = b_j, \quad j = 1, \dots, 2K + 1, \quad K \geq 0,$$

$$(3.11) \quad s_y - t_0 G(z, \omega, s) = (t - t_0) G(z, \omega, s) + B(z),$$

$$(3.12) \quad a(z)s(z) - t_0 Q(z, \omega, s) = (t - t_0) Q(z, \omega, s) + q(z).$$

Choosing arbitrary functions $\omega_0 \in C_\beta(\bar{D}) \cap W_{p_0}^1(D)$, $s_0 \in C_\beta^*(\bar{D})$, for instance $\omega_0(z) \equiv 0$, $s_0(z) \equiv 0$, we substitute $\omega_0(z), s_0(z)$ into the corresponding positions of the right hand sides in (3.8) - (3.12). By assumption, for t_0 the initial-boundary value problem (3.8) - (3.12) has a unique solution $[\omega_1(z), s_1(z)]$, $\omega_1 \in C_\beta(\bar{D}) \cap W_{p_0}^1(D)$, $s_1 \in C_\beta^*(\bar{D})$. Let us substitute $\omega_1(z), s_1(z)$ into the right hand sides of (3.8) - (3.12) and find unique solution $[\omega_2(z), s_2(z)]$, $\omega_2 \in C_\beta(\bar{D}) \cap W_{p_0}^1(D)$, $s_2 \in C_\beta^*(\bar{D})$ to this system. Thus, we obtain $[\omega_n(z), s_n(z)]$, $n = 1, 2, \dots$, satisfying

$$(3.13) \quad \omega_{n+1\bar{z}} - t_0 F(z, \omega_{n+1}, \omega_{n+1z}) = (t - t_0) F(z, \omega_n, \omega_{nz}) + A(z),$$

$$(3.14) \quad \begin{aligned} \operatorname{Re}[\bar{\lambda} \omega_{n+1}] - t_0 P(z, \omega_{n+1}, s_{n+1}) &= \\ &= (t - t_0) P(z, \omega_n s_n) + p(z) + h(z), \end{aligned}$$

$$(3.15) \quad \operatorname{Im}[\bar{\lambda}(a_j) \omega_{n+1}(a_j)] = b_j, \quad j = 1, \dots, 2K + 1, K \geq 0,$$

$$(3.16) \quad s_{n+1y} - t_0 G(z, \omega_{n+1}, s_{n+1}) = (t - t_0) G(z, \omega_n, s_n) + B(z),$$

$$(3.17) \quad a(z) s_{n+1} - t_0 Q(z, \omega_{n+1}, s_{n+1}) = (t - t_0) Q(z, \omega_n, s_n) + q(z).$$

Setting $W_{n+1} = \omega_{n+1} - \omega_n$, $S_{n+1} = s_{n+1} - s_n$ from (3.13) - (3.17), we have

$$(3.18) \quad \begin{aligned} W_{n+1\bar{z}} - t_0 [F(z, W_{n+1}, W_{n+1z}) - F(z, W_n, W_{nz})] &= \\ &= (t - t_0) [F(z, W_n, W_{nz}) - F(z, W_{n-1}, W_{n-1z})], \end{aligned}$$

$$(3.19) \quad \begin{aligned} \operatorname{Re}[\bar{\lambda} W_{n+1}] - t_0 [P(z, \omega_{n+1}, s_{n+1}) - P(z, \omega_n, s_n)] &= \\ &= (t - t_0) [P(z, \omega_n, s_n) - P(z, \omega_{n-1}, s_{n-1})] + h(z), \end{aligned}$$

$$(3.20) \quad \operatorname{Im}[\bar{\lambda}(a_j) W_{n+1}(a_j)] = 0, \quad j = 1, \dots, 2K + 1, K \geq 0,$$

$$(3.21) \quad \begin{aligned} S_{n+1y} - t_0 [G(z, \omega_{n+1}, s_{n+1}) - G(z, \omega_n, s_n)] &= \\ &= (t - t_0) [G(z, \omega_n, s_n) - G(z, \omega_{n-1}, s_{n-1})], \end{aligned}$$

$$(3.22) \quad \begin{aligned} a(z) S_{n+1} - t_0 [Q(z, \omega_{n+1}, s_{n+1}) - Q(z, \omega_n, s_n)] &= \\ &= (t - t_0) [Q(z, \omega_n, s_n) - Q(z, \omega_{n-1}, s_{n-1})]. \end{aligned}$$

By Condition C

$$(3.23) \quad \begin{aligned} L_{p_0} [F(z, W_n, W_{nz}) - F(z, W_{n-1}, W_{n-1z}), \bar{D}] &\leq \\ &\leq L_{p_0} [W_{nz}, \bar{D}] + 2k_0 C_\beta [W_n, \bar{D}], \end{aligned}$$

$$(3.24) \quad \begin{aligned} C_\alpha \{ &P[z(\zeta), \omega_n(z(\zeta)), s_n(z(\zeta))] - \\ &- P[z(\zeta), \omega_{n-1}(z(\zeta)), s_{n-1}(z(\zeta))], L \leq \\ &\leq \varepsilon \{ C_\alpha [W_n(z(\zeta)), L] + C_\alpha [S_n(z(\zeta)), \ell] \}, \end{aligned}$$

$$(3.25) \quad \begin{aligned} C_\beta [G(z, \omega_n, s_n) - G(z, \omega_{n-1}, s_{n-1}), \bar{D}] &\leq \\ &\leq 2k_0 C_\beta [W_n, \bar{D}] + k_0 C_\beta [S_n, \bar{D}], \end{aligned}$$

$$(3.26) \quad \begin{aligned} C_\beta[Q(z, \omega_n, s_n) - Q(z, \omega_{n-1}, s_{n-1}), \gamma] \leq \\ \leq k_2 C_\beta[W_n, \gamma] + \varepsilon C_\beta[S_n, \gamma] \end{aligned}$$

can be obtained.

According to the method in the proof of Theorem 2.2, we can conclude that

$$(3.27) \quad \begin{aligned} U_{n+1} := C_\beta[W_{n+1}, \bar{D}] + L_{p_0}[|W_{n+1\bar{z}}| + |W_{n+1z}|, \bar{D}] \leq \\ \leq |t - t_0| M_6 U_n, \end{aligned}$$

$$(3.28) \quad V_{n+1} := C_\beta^*[S_{n+1}, \bar{D}] \leq |t - t_0| M_6 V_n,$$

where $M_6 = M_6(q_0, p_0, k_0, \alpha, k, K, \varepsilon) \geq 0$.

Choosing $\delta = \frac{1}{2(M_6+1)}$, then for $|t - t_0| \leq \delta$, $0 \leq t \leq 1$, and $n > N + 1 > 1$, we can derive the inequality

$$U_{n+1} \leq \frac{1}{2} U_n \leq \frac{1}{2^N} U_1, \quad V_{n+1} \leq \frac{1}{2^N} V_1.$$

Moreover, if $n, m > N + 1$, then

$$(3.30) \quad \begin{aligned} C_\beta[\omega_n - \omega_m, \bar{D}] + L_{p_0}[|(\omega_n - \omega_m)_{\bar{z}}| + |(\omega_n - \omega_m)_z|, \bar{D}] \leq \\ \leq \frac{1}{2^N} \sum_{j=0}^{\infty} \frac{1}{2^j} U_1 = \frac{1}{2^{N-1}} U_1, \\ C_\beta^*[s_n - s_m, \bar{D}] \leq \frac{1}{2^{N-1}} C_\beta^*[s_1, \bar{D}]. \end{aligned}$$

This shows that $C_\beta[\omega_n - \omega_m, \bar{D}] + L_{p_0}[|(\omega_n - \omega_m)_{\bar{z}}| + |(\omega_n - \omega_m)_z|, \bar{D}] \rightarrow 0$, $C_\beta^*[s_n - s_m, \bar{D}] \rightarrow 0$, if $n, m \rightarrow \infty$. Hence there exist $\omega_* \in C_\beta(\bar{D}) \cap W_{p_0}^1(D)$, $s_* \in C_\beta^*(\bar{D})$, such that $C_\beta[\omega_n - \omega_*, \bar{D}] + L_{p_0}[|(\omega_n - \omega_*)_{\bar{z}}| + |(\omega_n - \omega_*)_z|, \bar{D}] \rightarrow 0$, $C_\beta^*[s_n - s_*, \bar{D}] \rightarrow 0$, as $n \rightarrow \infty$, and $[\omega_n(z), s_n(z)]$ is just a solution to Problem B' on E for (3.2) - (3.6). Thus, we know that when $t = 0, 1, \dots, [\frac{1}{\delta}]\delta, 1$, Problem B' for (3.2) - (3.6) is solvable. In particular, when $t = 1$, $A = 0$, $p = 0$, $B = 0$, $q = 0$, Problem B' i. e. Problem B for (3.1), (1.2) is solvable. \diamond

Theorem 3.2. *Under the same hypotheses as in Theorem 2.2, Problem B for (1.1), (1.2) has a solution.*

Proof. We introduce a bounded and closed convex set B_M in the Banach space $C(\bar{D}) \times C(\bar{D})$, the elements of which are vectors of functions $w = [\omega, s]$ satisfying the condition

$$(3.31) \quad C[\omega, \bar{D}] \leq M_4, \quad C[s, \bar{D}] \leq M_5,$$

where M_4, M_5 are the constants stated in (2.18), (2.19). We choose an arbitrary vector of functions $\Omega = [W, S] \in B_M$ and insert $W(z), S(z)$ into the appropriate positions of the complex equation (1.1). Following Theorem 3.1, there exists a solution $[\omega(z), s(z)]$ to the initial boundary value Problem B':

$$(3.32) \quad \begin{aligned} \omega_{\bar{z}} &= f(z, \omega, W, s, \omega_z), \\ f &= Q_1(z, W, \omega_z, s) \omega_z + Q_2(z, W, \omega_z, s) \bar{\omega}_{\bar{z}} + \\ &+ A_1(z, W, s) \omega + A_2(z, W, s) \bar{\omega} + A_3(z, W, s), \end{aligned}$$

and (1.2), (1.6), (1.10), (1.12), (1.7).

According to Theorem 2.2, the solution $[\omega(z), s(z)]$ satisfies the estimates (2.18) and (2.19), obviously $w = [\omega, s] \in B_M$. Denoting this mapping from $\Omega \in B_M$ onto w by $w = \mathcal{S}[\Omega]$, it is clear that \mathcal{S} is an operator which maps B_M onto a compact set in B_M .

To prove that \mathcal{S} is continuous in B_M , we select a sequence of vectors $[W_n, S_n](n = 0, 1, 2, \dots)$ satisfying the condition

$$(3.33) \quad C[W_n - W_0, \bar{D}] \rightarrow 0, C[S_n - S_0, \bar{D}] \rightarrow 0 \text{ as } n \rightarrow \infty$$

and consider the difference $w_n - w_0 = \mathcal{S}(\Omega_n) - \mathcal{S}(\Omega_0)$. We have

$$(3.34) \quad [\omega_n - \omega_0]_{\bar{z}} = f(z, \omega_n, W_n, \omega_{nz}) - f(z, \omega_0, W_0, \omega_{0z}),$$

$$(3.35) \quad \operatorname{Re}[\lambda(t)(\omega_n - \omega_0)] = P(z, \omega_n, s_n) - P(z, \omega_0, s_0) + h(t), t \in \Gamma,$$

$$(3.36) \quad \operatorname{Im}[\lambda(a_j)(\omega_n(a_j) - \omega_0(a_j))] = 0, j = 1, \dots, 2K + 1, K \geq 0,$$

$$(3.37) \quad (s_n - s_0)_y = G(z, w_n, s_n) - G(z, w_0, s_0),$$

$$(3.38) \quad a(t)[s_n - s_0] = Q(t, w_n, s_n) - Q(t, w_0, s_0), t \in \gamma.$$

The complex equation (3.34) can be written as

$$(3.39) \quad \begin{aligned} [\omega_n - \omega_0]_{\bar{z}} - [f(z, \omega_n, W_n, \omega_{nz}) - f(z, \omega_0, W_n, \omega_{0z})] &= c_n, \\ c_n &= f(z, \omega_0, W_n, \omega_{0z}) - f(z, \omega_0, W_0, \omega_{0z}). \end{aligned}$$

Using the method in the proof of Theorem 2.2 of Chapter 4 in [3] or Theorem 2.6 of Chapter 2 in [4], we can verify that $L_{p_0}[c_n, \bar{D}] \rightarrow 0$ as $n \rightarrow \infty$. Hence, applying the method used in the proof of Theorem 2.1,

$$(3.40) \quad C_\beta[\omega_n - \omega_0, \bar{D}], C_\beta[s_n - s_0, \bar{D}] \leq M_7 L_{p_0}[c_n, \bar{D}]$$

can be concluded where M_7 is a non-negative constant. If $n \rightarrow \infty$, then $C[\omega_n - \omega_0, \bar{D}] \rightarrow 0, C[s_n - s_0, \bar{D}] \rightarrow 0$. Hence, $w = S(\Omega)$ is a continuous

mapping from B_M onto a compact set in B_M . On the basis of the *Schauder fixed point theorem*, there exists a vector $w = [\omega, s] \in B_M$, so that $\omega = S(\omega)$, and $w = [\omega, s]$ is just a solution to Problem B for the system (1.1) and (1.2). \diamond

Theorem 3.3. *Suppose that the system (1.1), (1.2) satisfies the same conditions as in Theorem 2.2, then the following statement holds*

(1) *If $K \geq 0$, Problem A for (1.1), (1.2) is solvable.*

(2) *If $K < 0$, there are $-2K - 1$ conditions for Problem A to be solvable.*

Proof. Let us substitute the solution $[\omega(z), s(z)]$ to Problem B into the boundary condition (1.10). If $h(z) = 0, z \in \Gamma$, then $[\omega(z), s(z)]$ is also a solution to Problem A for (1.1), (1.2). The total number of real equalities in $h(z) = 0$ is just the total number of conditions stated in the theorem. \diamond

Finally, in order to discuss the uniqueness of the solution to Problem B and Problem A for (1.1), (1.2) the following additional condition is imposed.

There exist $A_1^*, A_2^* \in L_{p_0}(\bar{D})$, with $L_{p_0}[A_2^*, \bar{D}]$ small enough, such that

$$(3.41) \quad F(z, \omega_1, U, s_1) - F(z, \omega_2, U, s_2) = A_1^*(\omega_1 - \omega_2) + A_2^*(s_1 - s_2),$$

for any functions $\omega_j, s_j \in C_\beta(\bar{D}), j = 1, 2$, and $U \in L_{p_0}(\bar{D})$ ($2 < p_0 < p$).

Theorem 3.4. *(1.1), (1.2) satisfies Condition C and (3.41), and the constant ε in (1.3), (1.8), (1.9) is small enough, then the solutions to Problem B are unique.*

Proof. Let $[\omega_1(z), s_1(z)], [\omega_2(z), s_2(z)]$ be two solutions to Problem B for (1.1), (1.2). It is clear that $[\omega, s] = [\omega_1 - \omega_2, s_1 - s_2]$ is a solution to the initial-boundary value problem

$$\omega_{\bar{z}} = Q\omega_z + A_1^*\omega + A_2^*s,$$

$$Q = \begin{cases} \frac{F(z, \omega_1, \omega_{1z}, s_1) - F(z, \omega_1, \omega_{2z}, s_2)}{\omega_z}, & \omega_z \neq 0, \\ 0, & \omega_z = 0; \end{cases}$$

$$s_y = B_1^*\omega + B_2^*\bar{\omega} + B_3^*s,$$

$$\operatorname{Re}[\bar{\lambda}(t)\omega(t)] = P(t, \omega_1, s_1) - P(t, \omega_2, s_2) + h(t), t \in \Gamma,$$

$$\operatorname{Im}[\bar{\lambda}(a_j)\omega(a_j)] = 0, j = 1, 2, \dots, 2K + 1 (0 \leq K);$$

$$a(t)s(t) = Q(t, \omega_1, s_1) - Q(t, \omega_2, s_2), t \in \gamma.$$

With the method used in the proof of Theorem 2.2, we can show

$$\begin{aligned} C_\beta[\omega, \bar{D}] + L_{p_0}[|\omega_{\bar{z}}| + |\omega_z|, \bar{D}] &= 0, \\ C_\beta^*(s, \bar{D}) &= 0, \end{aligned}$$

so that $\omega(z) \equiv 0, s(z) \equiv 0$, i.e. $\omega_1(z) \equiv \omega_2(z)s_1(z) \equiv s_2(z)$ in \bar{D} . \diamond

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